

CV	Description	Area	Value*
1	Locomotive address	DCC: 1 - 127 Mot: 1 - 80	3
2	Minimum speed (the speed from 0 until the locomotive is running at speed step 1)	0 - 255	1
3	Acceleration delay	0 - 255	30
4	Braking rate	0 - 255	30
5	Maximum speed (must be greater than CV 2)	0 - 255	200
6	Average speed (must be greater than CV 2 and less than CV 5)	0 - 255	100
7	Software version (The processor can be updated)	-	differently.
8	anufacturer identification decoder reset, CV8 = 8	-	162
	Decoder operating mode	Value*	
12	Bit 0=1 DC (analog operation; direct current) on	*1	0 - 117
	Bit 2=1 DCC data format on	*4	
	Bit 4=1 AC (analog 3-rail operation; alternating current) on	*16	
	Bit 5=1 Motorola® data format on	*32	
17	Long locomotive address	1 - 10239	1000
18	17 = high Byte	192 - 231	195
	18 = low Byte	0 - 255	232
	Brake signal settings (automatic stop)	Value*	
27	Bit 0 = 1 -> ABC (Automatic Brake Control) right rail positive	1	0 - 51
	Bit 1 = 1 -> ABC left rail positive	2	
	Bit 4 = 1 -> DC; opposite direction of travel	16	
	Bit 5 = 1 -> DC; same direction of travel	32	
	DCC standard configuration	Value*	
29	Bit 0=0 Normal direction of travel	*0	0 - 63
	Bit 0=1 Opposite direction of travel	1	
	Bit 1=0 14 speed steps	0	
	Bit 1=1 28 speed steps	*2	
	Bit 2=0 Digital mode only	0	
	Bit 2=1 Automatic analog/digital recognition	*4	
	Bit 3=0 RailCom® turned off	0	
	Bit 3=1 RailCom® turned on	*8	
	Bit 4=0 Speed steps over CV 2, 5, and 6	*0	
	Bit 4=1 Use the characteristic curve from CV 67 - 94	16	
	Bit 5=0 Short address (CV1)	*0	
	Bit 5=1 Long address (CV 17/18)	32	
30	Error log for motor, function outputs, temperature, and sound		
	1 = Motor error, 2 = Temperature exceeded, 4 = Function output error, 8 = Soundflash error, 16 = Sound transmission error	0 - 31	0

* Factory setting

Function assignments

F0	Light	F8	Door
F1	Driving noise	F9	Cab Window
F2	Horn	F10	Passenger Car Window
F3 *	Interiorlight	F11	Clickety-Clack
F4	Station Announcement 1	F12	Curve Squeal
F5	Station Announcement 2	F13	Volumeregulator
F6	Conductor's Whistle	F14	Tunnel mode
F7	Switching Gear	F15	Language switch

* version-dependent

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PIKO SmartDecoder XP Sound Next18
for Electric Railcar (GTW) Stadler N
multiprotocol



NOTE: Detailed information on the PIKO SmartDecoder XP Sound is available as a PDF file on our Webshop on the page of the respective item number. The file contains a full description of all functions and operating possibilities for the new SmartDecoder XP Sound.

Description

This PIKO SmartDecoder XP Sound Next18 is a compact, very powerful multiprotocol sound decoder of the latest generation with 12 bit sounds and high sample rate, 8 sound channels, an output power of 2.5 watts and a significantly increased memory depth. The sound decoder provides a noise-free sound experience at the highest level. It complies with the current RC standards in all areas and can be used in DCC and Motorola® digital systems. Furthermore, it also works in analog mode with DC or AC voltage. The sound decoder is RailCom® as well as RailCom Plus® capable. The innovative PIKO SmartDecoder XP Sound with many braking section functions independently recognizes the respective operating mode and has a wide variety of setting options for the additional functions.

The load-controlled sound decoder works with a fundamentally newly developed auto-adaptive motor control for silky-smooth operation and is thus suitable not only for DC motors, but also for bell armature motors up to a continuous current consumption of 1 A. The sound decoder masters ABC braking, ABC automatic shuttle as well as ABC slow speed. The setting of the motor characteristic is done via the minimum, average and maximum speed (simple characteristic), or via the extended characteristic with individual settings for 28 speed steps. The sound decoder has two direction-dependent lighting outputs, as well as four (two of which are logic) additional special function outputs that can be switched via function keys up to F68 (DCC). The shunting mode with extended slow speed range, the three possible starting and braking delays, as well as the many vehicle sounds are also switchable via function keys. Depending on the project, the sound module can control specific function outputs as well as the decoder's motor output. For example, the lighting of a diesel locomotive flickers when the engine is started. Due to the advanced power management the PIKO SmartDecoder XP is supported in case of short-term voltage loss.

Installing the PIKO SmartDecoder XP Sound

Remove the jumper plug from your model's Next18 interface. Insert the new sound decoder into the interface socket. Please install the loudspeaker as shown in the graphic of the "Spare parts list". Check for crossed wires and short circuits before and after reinstalling the shell. Place the model on your programming track with programming mode activated on your DCC system. During programming or when reading the model's DCC address, a small amount of current will flow through the model, which does not affect the decoder; even in the event of a short circuit.

Special functions A1 to A4

The special function outputs A1 to A4 of the sound decoder can only be used if the desired consumers are already connected to the Next18 interface in the vehicle, or solder pads are present on the main board. Outputs A3 & A4 provide logic levels and must be wired accordingly on the main board.

A short circuit in the motor, lighting, pick-up wiper, or wheelsets can destroy the decoder as well as the electronics of the model!

First-time use of the decoder (state of delivery)

Enter address 3 on your DCC control system. Depending on the data format used to address the sound decoder, the locomotive runs in DCC mode with 28 speed steps or in Motorola® mode. When using a RailCom Plus®-enabled DCC system, the decoder is recognized automatic and can be operated immediately. If the decoder is used on a conventional analog layout, it can be controlled with a DC or AC power pack. The decoder will automatically detect the layout's operating mode.

NOTE: In analog mode, your model will only start at a higher voltage than what you may accustomed to when operating analog models. You will need to turn the throttle up for the model to start operating.

Function outputs in analog mode

It is possible to program the decoder so that function keys F0 - F12 (as they are assigned in the function mapping) can also be activated in analog mode. To do this, CVs 13 & 14 must first be programmed with a DCC central control unit. The corresponding values can be found in the CV table of the detailed operating instructions. The light function F0 and the driving noise F1 are switched on ex works.

Motorola®

The decoder utilizes 4 Motorola® addresses to access functions F1 - F 16, when using a Motorola—based command station. The three sequence addresses for the functions F5 - F16 are ascending to the decoder address and can be activated in CV61 as required by the values 1 (F5 - F8), 2 (F5 - F12), or 3 (F5 - F16).

Configuration of CVs

In addition to the decoder address, the indexed CVs of a locomotive decoder are the most important CVs. These are the CVs 29, 50 and 51 in the PIKO SmartDecoder XP Sound. As a rule, an indexed CV contains various basic settings of a decoder, such as reversing the direction of travel. CV calculation examples can be found in the detailed operating instructions.

RailCom®, RailCom Plus®

In the sound decoder, CV29 (RailCom®) can be turned on or off via bit 3. If RailCom Plus® is turned on, the decoder will be automatically recognized by a RailCom Plus®-enabled DCC control system (i.e. PIKO SmartControl) and a locomotive icon, decoder name, and its special function icons will appear on the control system's screen. With RailCom Plus® technology, no locomotive data has to be stored in the DCC central control unit and no locomotive addresses have to be programmed into the decoder.

Braking

The sound decoder understands the following braking methods:

Märklin® braking section (brakes with analog DC voltage)

DCC braking function

ABC (Automatic Brake Control) braking section

The sound decoder can stop the model with two adjustable braking distances that are accurate down to the centimeter. More information on "braking behavior" can be found in the detailed operating instructions for PIKO SmartDecoder XP Sound.

Function outputs

A comprehensive description of all options related to the function outputs can be found in the detailed operating instructions.

Simple function mapping (CV96 = 1)

In the **simple function mapping** (CVs 33 - 46) the assignments of the switching tasks like lighting and special function outputs can be freely assigned to the function keys F0 to F12 of the digital central unit. The switchable acceleration, braking delay and the shunting gear can be assigned to any function keys in CVs 156 and 157. More detailed information can be found in the detailed operating instructions.

Smoke generator control

A smoke generator can be connected to the outputs A1 and A2, which is controlled by the sound decoder load-dependent (factory setting) or also speed-dependent. The assignment to the function keys is done exclusively via the extended function mapping.

Extended function mapping (CV96 = 6, factory setting)

Due to its complex nature, extended **function mapping** cannot easily be set by programming individual CVs. To work with extended **function mapping**, you will need the PIKO SmartProgrammer device (#56415) and, if desired, the PIKO SmartTester (#56416). Detailed information on extended function mapping is available in the instruction manual.

Servo control

The sound decoder enables the control of servo motors via the function outputs A1 and A2. The assignment to the function keys is done exclusively via the extended function mapping.

The use of a servo with the decoder requires electronics expertise.

Further information can be found in the detailed operating instructions.

ATTENTION: Soldering on the decoder should only be carried out by experienced specialists with the appropriate tools. Decoders damaged by improper handling will not be covered by the warranty.

Sound settings

The overall volume can be set as desired by programming CV63 in a value range of 0 - 255.

NOTE: In order to play a PIKO sound on the sound decoder, the test and programming device requires PIKO SmartProgrammer (#56415) and (optional) the PIKO SmartTester (#56416).

All further information about the sound section of the PIKO SmartDecoder XP Sound as well as the available For setting options, please refer to the detailed operating instructions.

Factory reset

To restore the sound decoder to its factory settings, program CV8 to a value of 8.

Programming

Configuration variables (CVs) form the basis of all the decoder's settings. This decoder can be used with the PIKO SmartControl_{wlan}, PIKO SmartControl_{light} DCC system or any other Motorola-based system.

For more information on programming options, please refer to the instruction manual.

Update

The PIKO SmartDecoder XP can be updated. To perform an update, you need either the PIKO SmartProgrammer (#56415) or the digital system PIKO SmartControl_{wlan} (#55821).

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RailCom® and RailComPlus® are registered trademarks of Lenz Elektronik GmbH, 35398 Gießen

NOTE: This product is not a toy and is not suitable for children under the age of 14. Any liability for damage of any kind caused by improper use or failure to observe these instructions is excluded.

Service:

Internet: www.piko.de

E-Mail: info@piko.de

Hotline: Di + Do 16-18 Uhr

Service: If you wish to return an item, please send it to us along with a copy of the receipt and the completed return form, which you can find in our online store under "Returns and Refunds."

Warranty Statement

Each decoder module is fully tested before shipment. Nevertheless, should a malfunction occur within the 2-year warranty period, we will repair the module free of charge on presentation of the proof of purchase. This warranty is voided if the unit has been damaged by improper use. Please note that, according to the German Electromagnetic Compatibility Law (EMV-Gesetz), the decoder module may only be used inside models bearing the CE mark.

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