

| CV | Description | Area | Value* |
|----------|--|---|--------------------|
| 1 | Locomotive address | DCC: 1 - 127 Mot: 1 - 80 | 3 |
| 2 | Minimum speed (the speed from 0 until the locomotive is running at speed step 1) | 0 - 255 | 0 |
| 3 | Acceleration delay | 0 - 255 | 30 |
| 4 | Braking delay | 0 - 255 | 30 |
| 5 | Maximum speed (must be greater than CV 2) | 0 - 255 | 200 |
| 6 | Average speed (must be greater than CV 2 and less than CV 5) | 0 - 255 | 100 |
| 7 | Firmware version (The processor can be updated) | - | differently |
| 8 | Manufacturer's ID Decoderreset CV8 = 8 | - | 162 |
| 12 | Decoder operating mode Bit 0=1 DC (analog operation; direct current) on Bit 2=1 DCC data format on Bit 4=1 AC (analog 3-rail operation; alternating current) on Bit 5=1 Motorola® data format on Bit 6=1 mfx® data format on | Value *1 *4 *16 *32 *64 | 0 - 117 117 |
| 17 18 | Long locomotive address 17 = high Byte 18 = low Byte | 1 - 10239 192 - 231 0 - 255 | 1000 195 232 |
| 27 | Brake signal settings (automatic stop) Bit 0 = 1 -> ABC (Automatic Brake Control) right rail positive Bit 1 = 1 -> ABC left rail positive Bit 4 = 1 -> DC; opposite direction of travel Bit 5 = 1 -> DC; same direction of travel | Value 1 2 16 32 | 0 - 51 0 |
| 29 | DCC standard configuration Bit 0=0 Normal direction of travel Bit 0=1 Opposite direction of travel Bit 1=0 14 speed steps Bit 1=1 28 speed steps Bit 2=0 Digital mode only Bit 2=1 Automatic analog/digital recognition Bit 3=0 RailCom® turned off Bit 3=1 RailCom® turned on Bit 4=0 Speed steps over CV 2, 5, and 6 Bit 4=1 Use the characteristic curve from CV 67 - 94 Bit 5=0 Short address (CV1) Bit 5=1 Long address (CV 17/18) | Value *0 1 0 *2 0 *4 0 *8 *0 16 *0 32 | 0 - 63 14 |
| 30 | Error codes for the motor, thermal overload, and function outputs: 1 = motor error, 2 = thermal overload error, 4 = function output error | 0 - 7 | 0 |

* set ex works

Function assignments

| | | | | | |
|----|-------------------|----|----------------------|-----|------------------|
| F0 | Light | F5 | Station Announcement | F10 | Sanding |
| F1 | Traveling Sound | F6 | Conductor's Whistle | F11 | Volume Regulator |
| F2 | High Tone Horn | F7 | Switching Gear | F12 | Tunnel mode |
| F3 | Low Tone Horn | F8 | Door | | |
| F4 | Interior Lighting | F9 | Cab Door | | |

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#56619 PIKO SmartDecoder XP Sound NEM652
for Diesel railcar VT 612 Regioswinger H0
multiprotocol, fits mfx® included



NOTE: Detailed information on the PIKO SmartDecoder XP Sound is available as a PDF file on our Webshop on the page of the respective item number. The file contains a full description of all functions and operating possibilities for the new SmartDecoder XP Sound.

Description

The state-of-the-art PIKO SmartDecoder XP Sound inside in this PIKO locomotive is a compact yet powerful multi-protocol NEM652 sound decoder. It features high fidelity, 12 bit 8-channel sound with 2.5 watts of output that ensures distortion-free sound at all levels. It complies with the current RCN standards in all areas. The decoder can be used on DCC, mfx®, and Motorola® digital systems as well as traditional DC or AC analog layouts. It automatically senses what operating mode is used on your layout and is RailCom®/RailCom Plus® compatible. The PIKO SmartDecoder XP Sound features several programmable braking distance functions in addition to numerous other programmable functions.

The PIKO SmartDecoder XP Sound is load-regulated and features auto-adaptive motor control that works with a fundamentally newly developed traditional DC motors for a silky smooth ride as well as 1.2 Amp coreless motors. The decoder will also tolerate a temporary current draw up to 2 Amps. The sound decoder masters ABC braking, ABC shuttle automatic, as well as ABC slow speed. The motor speed table can be set using the minimum, median, and maximum motor speed (simple curve), or by the user-programmable 28-speed step extended curve. The decoder features two directional lighting outputs well as via an additional special function output that can be activated using function keys up to F68 (DCC). The switching (shunting) gear, with extended slow speed range, the three possible starting and braking delays, as well as the many vehicle sounds are also switchable via function keys. The sound part can control specified function outputs as well as the motor output of the decoder. The PIKO SmartDecoder XP is supported by the further developed power management in case of short-term voltage loss..

Installing the PIKO SmartDecoder XP Sound

Remove the jumper plug from your model's NEM 652 interface. At the same place insert the 8-pin plug of the decoder carefully into the interface socket. Please note the coding of PIN 1 note. If the plug is turned 180°, the locomotive will run in the wrong direction and the light will not work. Check for crossed wires and short circuits before and after reinstalling the shell. Place the model on your programming track with programming mode activated on your DCC system. During programming or when reading the model's DCC address, a small amount of current will flow through the model, which does not affect the decoder; even in the event of a short circuit.

Special function A1

The special function output A1 of the PIKO SmartDecoder XP can only be used if the desired consumer is already connected to the NEM 652 interface in the vehicle, or if there are solder pads on the main board.

A short circuit in the motor, lighting, pick-up wiper, or wheelsets can destroy the decoder as well as the electronics of the model!

First-time use of the decoder (state of delivery)

Enter address 3 on your digital control system. Depending on the data format used to address the sound decoder, the locomotive runs in DCC mode with 28 speed steps or in Motorola® mode. When using a RailCom Plus®-enabled system or with an mfx®-capable system, the decoder is detected automatically and can be operated immediately. If the decoder is used on a conventional analog layout, it can be controlled with a DC or AC power pack. The decoder will automatically detect the layout's operating mode.

NOTE: In DC mode, your vehicle will not start until the voltage is higher (speed control turned up further) than you may have been used to when operating with analog vehicles.

Function outputs in analog mode

It is possible to program the decoder so that function keys F0 - F12 (as they are assigned in the function mapping) can also be activated in analog mode. To do this, CVs 13 & 14 must first be programmed with a central control unit. The corresponding values can be found in the CV table of the detailed operating instructions. The light function F0 and the motor sound F1 are switched on ex works.

Motorola®

The decoder utilizes 4 Motorola® addresses to access functions F1 - F 16, when using a Motorola—based command station. The three sequence addresses for the functions F5 - F16 are ascending to the decoder address and can be activated in CV61 as required by the values 1 (F5 - F8), 2 (F5 - F12), or 3 (F5 - F16).

Configuration of CVs

CVs 12 and 29 control the operating mode and configuration CVs, respectively. As a rule, an indexed CV contains various basic settings of a decoder, such as reversing the direction of travel. CV calculation examples can be found in the detailed operating instructions.

RailCom®, RailCom Plus®

In the sound decoder, CV29 (RailCom®) can be turned on or off via bit 3. The decoder is automatically recognized by RailCom Plus® - equipped command stations (like PIKO SmartControl^{wlan}) if the RailCom Plus® option is activated in CV 28. The decoder name, locomotive symbol, and special function symbols will appear automatically on your control device's screen. With RailCom Plus® technology, no locomotive data has to be stored in the DCC central control unit and no locomotive addresses have to be programmed into the decoder.

fits mfx®

The PIKO SmartDecoder XP Sound also masters the mfx® data format and is fits mfx® certified. If the digital command station used is mfx® capable, the sound decoder automatically registers with its locomotive symbol, decoder name and its complete special function symbols. This mfx® technology means that no locomotive data needs to be stored in the command station and no locomotive addresses need to be programmed into the sound decoder.

Braking

The sound decoder understands the following braking methods:

Märklin® braking section (brakes with analog DC voltage)

DCC braking function

ABC (Automatic Brake Control) braking section

The decoder's adjustable braking distance can bring the train to a stop within a centimeter of a signal. More information on "braking behavior" can be found in the detailed operating instructions for

PIKO SmartDecoder XP Sound.

Shunting speed (RG)

The desired function key F0 - F68, via which the shunting speed (half speed) can be switched on, is entered in CV157.

Starting and braking delays (ABV)

The desired function key F0 - F68, which can be used to switch off the ABV, is entered in CV156. The values of the starting and braking delays can be changed in CVs 3 and 4.

Function outputs

A comprehensive description of all options related to the function outputs can be found in the detailed operating instructions.

Simple and extended function mapping

In the simple function mapping according to RCN-225 (CVs 33 - 46) the switching tasks such as lighting and special function output can be freely assigned to the function keys F0 to F12 of the digital command station.

The switchable starting and braking delay and the shunting gear can be assigned to any function key up to F68 in CVs 156 and 157 can be assigned to any function keys up to F68. More information can be found in the detailed operating instructions.

Smoke generator control

A smoke generator can be connected to output A1, which can be controlled by the decoder either load- or speed-dependent. speed-dependent by the decoder. The assignment to the function keys is done exclusively via the extended function mapping extended function mapping.

Extended function mapping

Due to its complex nature, extended **function mapping** cannot easily be set by programming individual CVs. To work with extended **function mapping**, you will need the PIKO SmartProgrammer device (#56415) and, if desired, the PIKO SmartTester (#56416). Detailed information on extended function mapping is available in the instruction manual.

Servo control

The decoder enables the control of a servo motor via function output A1. The assignment to the function keys is done exclusively via the extended function mapping.

The use of a servo with the decoder requires electronics expertise.

Further information can be found in the detailed operating instructions.

ATTENTION: Soldering on the decoder should only be carried out by experienced specialists with the appropriate tools. Decoders damaged by improper handling will not be covered by the warranty.

Sound settings

To change the overall sound volume of the SmartDecoder XP Sound, first program CV31 to a value of 16 and CV32 to a value of 0.

This will take you to the programming area for setting the total volume. You can now set this as you wish in CV257 in the value range 0 - 255.

NOTE: In order to play a PIKO sound on the sound decoder, the test and programming device requires PIKO SmartProgrammer (#56415) and (optional) the PIKO SmartTester (#56416).

All further information about the sound section of the PIKO SmartDecoder XP Sound as well as the available For setting options, please refer to the detailed operating instructions.

Factory reset

To restore the sound decoder to its factory settings, program CV8 to a value of 8.

Programming

Configuration variables (CVs) form the basis of all the decoder's settings. This decoder can be used with the PIKO SmartControl^{wlan}, PIKO SmartControl^{light}, DCC system, the PIKO SmartControl DCC system, or any other Motorola-based system.

For more information on programming options, please refer to the instruction manual.

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Motorola® is a registered trademark of Motorola Inc. Tempe, (Phoenix) Arizona / USA
RailCom® and RailComPlus® are registered trademarks of Lenz Elektronik GmbH, 35398 Gießen

NOTE: This product is not a toy and is not suitable for children under the age of 14. Any liability for damage of any kind caused by improper use or failure to observe these instructions is excluded.

Service:

Internet: www.piko.de

E-Mail: info@piko.de

In the event of a defective decoder, please return the decoder module to PIKO along with proof of purchase, the decoder address, and a short description of the problem.

Warranty Statement

Each decoder module is fully tested before shipment. Nevertheless, should a malfunction occur within the 2-year warranty period, we will repair the module free of charge on presentation of the proof of purchase. This warranty is voided if the unit has been damaged by improper use. Please note that, according to the German Electromagnetic Compatibility Law (EMV-Gesetz), the decoder module may only be used inside models bearing the CE mark.

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