

CV	Description	Area	Value*
1	Locomotive address	DCC: 1 - 127 Motorola: 1 - 80	3
2	Minimum speed (the speed from 0 until the locomotive is running at speed step 1)	0 - 255	5
3	Acceleration delay	0 - 255	80
4	Braking delay	0 - 255	80
5	Maximum speed (must be greater than CV 2)	0 - 255	124
6	Average speed (must be greater than CV 2 and less than CV 5)	0 - 255	62
7	Firmware version (The processor can be updated)	-	differently
8	Manufacturer's ID Decoderreset CV8 = 8	-	162
12	Decoder operating mode	Value	0 - 117
	Bit 0=1 DC (analog operation; direct current) on	*1	
	Bit 2=1 DCC data format on	*4	
	Bit 4=1 AC (analog 3-rail operation; alternating current) on	*16	
	Bit 5=1 Motorola® data format on	*32	
17 18	Long locomotive address	1 - 10239	1000
	17 = high Byte 18 = low Byte	192 - 231 0 - 255	195 232
27	Brake signal settings (automatic stop)	Value	0 - 51
	Bit 0 = 1 -> ABC (Automatic Brake Control) right rail positive	1	
	Bit 1 = 1 -> ABC left rail positive	2	
	Bit 4 = 1 -> DC; opposite direction of travel	16	
	Bit 5 = 1 -> DC; same direction of travel	32	
29	DCC standard configuration	Value	0 - 63
	Bit 0=0 Normal direction of travel	*0	
	Bit 0=1 Opposite direction of travel	1	
	Bit 1=0 14 speed steps	0	
	Bit 1=1 28 speed steps	*2	
	Bit 2=0 Digital mode only	0	
	Bit 2=1 Automatic analog/digital recognition	*4	
	Bit 3=0 RailCom® turned off	0	
	Bit 3=1 RailCom® turned on	*8	
	Bit 4=0 Speed steps over CV 2, 5, and 6	*0	
	Bit 4=1 Use the characteristic curve from CV 67 - 94	16	
Bit 5=0 Short address (CV1)	*0		
Bit 5=1 Long address (CV 17/18)	32		
30	Error codes for the motor, thermal overload, function outputs and sound: 1 = motor error, 2 = thermal overload error, 4 = function output error, 8 = fault soundflash, 16 = fault sound transmission	0 - 31	0

* set ex works

Function assignments

F0	Light	F10	Air Valve Release	F20	Curve Squeal
F1	Engine	F11	Coupling	F21	Cab Door
F2	High Tone Horn	F12	Station Announcement 1	F22	Engine Room Door
F3	Low Tone Horn	F13	Station Announcement 2	F23	Cab Window
F4	Destination Board	F14	Station Announcement 3	F24	Clickety-Clack
F5	Engineer's Greeting	F15	Conductor's Whistle	F25	Volume Regulator
F6	Battery Main Switch	F16	Air Compressor	F26	Tunnel mode
F7	Switching Gear	F17	Change language	F27	-
F8	Train Lighting: Engine pulling	F18	Sanding	F28	-
F9	Train Lighting: Engine pushing	F19	Break Test		



#56553 PIKO SmartDecoder XP Sound PluX22
for Diesel locomotives BR 247 Vectron H0
multiprotocol, fits mfx® included



NOTE: Detailed information on the PIKO SmartDecoder XP Sound is available as a PDF file on our **Webshop** on the page of the respective item number. The file contains a full description of all functions and operating possibilities for the new SmartDecoder XP Sound.

Description

The state-of-the-art PIKO SmartDecoder XP Sound inside in this PIKO locomotive is a compact yet powerful multi-protocol PluX22 sound decoder. It features high fidelity, 12 bit 8-channel sound with 2.5 watts of output that ensures distortion-free sound at all levels. It complies with the current RC standards in all areas. The decoder can be used on DCC, mfx®, and Motorola® digital systems as well as traditional DC or AC analog layouts. It automatically senses what operating mode is used on your layout and is RailCom®/RailCom Plus® compatible. The PIKO SmartDecoder XP Sound features several programmable braking distance functions in addition to numerous other programmable functions.

The PIKO SmartDecoder XP Sound is load-regulated and features auto-adaptive motor control that works with of a fundamentally newly developed traditional DC motors for a silky smooth ride as well as 1.2 Amp coreless motors. The decoder will also tolerate a temporary current draw up to 2 Amps. The motor speed table can be set using the minimum, median, and maximum motor speed (simple curve), or by the user-programable 28-speed step extended curve. The decoder features two directional lighting outputs and seven additional special function outputs that can be activated using function keys up to F68 (DCC). The switching (shunting) gear, with extended slow speed range, the three possible starting and braking delays, as well as the many vehicle sounds are also switchable via function keys. Depending on the project, the sound module can control specific function outputs as well as the decoder's motor output. For example, the lighting of a diesel locomotive flickers when the engine is started. The PIKO SmartDecoder XP is supported by the further developed power management in case of short-term voltage loss.

Installing the PIKO SmartDecoder XP Sound

Remove the jumper plug from your model's PluX22 interface. Insert the new sound decoder into the interface socket. Note that PIN 11 is missing on the new decoder. Please install the loudspeaker as shown in the graphic of the "Spare parts list". Check for crossed wires and short circuits before and after reinstalling the shell. Place the model on your programming track with programming mode activated on your DCC system. During programming or when reading the model's DCC address, a small amount of current will flow through the model, which does not affect the decoder; even in the event of a short circuit.

Special function outputs A1 to A7

The decoder's special function outputs A1 to A7 can only be activated if the desired functions are already connected to the model's PluX22 interface or if solder pads are available for the special function outputs on the main circuit board.

A short circuit in the motor, lighting, pick-up wiper, or wheelsets can destroy the decoder as well as the electronics of the model!

First-time use of the decoder (state of delivery)

Enter address 3 on your digital control system. Depending on the data format used to address the sound decoder, the locomotive runs in DCC mode with 28 speed steps or in Motorola® mode. When using a RailCom Plus®-enabled system or with an mfx®-capable system, the decoder is detected automatically and can be operated immediately. If the decoder is used on a conventional analog layout, it can be controlled with a DC or AC power pack. The decoder will automatically detect the layout's operating mode.

NOTE: In analog mode, your vehicle will not start until the voltage is higher (speed control turned up further) than you may have been used to when operating with analog vehicles.

Function outputs in analog mode

It is possible to program the decoder so that function keys F0 - F12 (as they are assigned in the function mapping) can also be activated in analog mode. To do this, CVs 13 & 14 must first be programmed with a central control unit. The corresponding values can be found in the CV table of the detailed operating instructions. The light function F0 and the traveling sound F1 are switched on at the factory.

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Motorola®

The decoder utilizes 4 Motorola® addresses to access functions F1 - F 16, when using a Motorola—based command station. The three sequence addresses for the functions F5 - F16 are ascending to the decoder address and can be activated in CV61 as required by the values 1 (F5 - F8), 2 (F5 - F12), or 3 (F5 - F16).

Configuration of CVs

CVs 12 and 29 control the operating mode and configuration CVs, respectively. As a rule, an indexed CV contains various basic settings of a decoder, such as reversing the direction of travel. CV calculation examples can be found in the detailed operating instructions.

RailCom®, RailCom Plus®

In the sound decoder, CV29 (RailCom®) can be turned on or off via bit 3. The decoder is automatically recognized by RailCom Plus® - equipped command stations (like PIKO SmartControl^{wlan}) if the RailCom Plus® option is activated in CV 28. The decoder name, locomotive symbol, and special function symbols will appear automatically on your control device's screen. With RailCom Plus® technology, no locomotive data has to be stored in the DCC central control unit and no locomotive addresses have to be programmed into the decoder.

fits mfx®

The PIKO SmartDecoder XP Sound also masters the mfx® data format and is fits mfx® certified. If the digital command station used is mfx® capable, the sound decoder automatically registers with its locomotive symbol, decoder name and its complete special function symbols. This mfx® technology means that no locomotive data needs to be stored in the command station and no locomotive addresses need to be programmed into the sound decoder.

Braking

The sound decoder understands the following braking methods:

Märklin® braking section (brakes with analog DC voltage)

DCC braking function

ABC (Automatic Brake Control) braking section

The decoder's adjustable braking distance can bring the train to a stop within a centimeter of a signal. More

information on "braking behavior" can be found in the detailed operating instructions for

PIKO SmartDecoder XP Sound.

Function outputs

A comprehensive description of all options related to the function outputs can be found in the detailed operating instructions.

Simple function mapping (CV96 = 1)

In the **simple function mapping** (CVs 33 - 46), the assignments of the switching tasks such as lighting and special function outputs can be freely assigned to the function keys F0 to F12 of the digital central unit. The switchable starting and braking delay and the shunting mode can be assigned to any function key in CVs 156 and 157. More detailed information can be found in the detailed operating instructions.

Smoke generator control

A smoke generator can be connected to outputs A1 to A7 which are load-sensitive and react to the model's speed.

Function key assignment is done using extended function mapping.

Electric coupler control

PIKO electric couplers are operated by tiny copper wire resistance wires which heat up when the decoder sends current through them. The heat causes the wires to expand, causing the coupler hook to move to the uncoupled position. The model can then back away from the car. With the appropriate decoder settings, function outputs A4 and A5 will automatically switch off after a user-adjustable time without having to press their function key.

Switching (shunting) scenario, remote coupling/uncoupling

If your layout has remote electric uncouplers installed, you can program the locomotive decoder to perform a switching scenario like the following:

- 1) The locomotive runs in one direction for a certain distance.
- 2) The locomotive stops and reverses direction.
- 3) The locomotive uncouples and moves back from the uncoupled car for a certain distance.
- 4) The locomotive stops, and resumes switching..

Extended function mapping (CV96 = 6, factory setting)

Due to its complex nature, extended **function mapping** cannot easily be set by programming individual CVs. To work with extended **function mapping**, you will need the PIKO SmartProgrammer device (#56415) and, if desired, the PIKO SmartTester (#56416). Detailed information on extended function mapping is available in the instruction manual.

Servo control

The sound decoder enables the control of servo motors via all function outputs. The assignment to the function keys is done exclusively via the extended function mapping.

The use of a servo with the decoder requires electronics expertise.

Further information can be found in the detailed operating instructions.

ATTENTION: Soldering on the decoder should only be carried out by experienced specialists with the appropriate tools. Decoders damaged by improper handling will not be covered by the warranty.

Sound settings

To change the overall sound volume of the SmartDecoder XP Sound, first program CV31 to a value of 16 and CV32 to a value of 0.

This will take you to the programming area for setting the total volume. You can now set this as you wish in CV257 in the value range 0 - 255.

NOTE: In order to play a PIKO sound on the sound decoder, the test and programming device requires PIKO SmartProgrammer (#56415) and (optional) the PIKO SmartTester (#56416).

All further information about the sound section of the PIKO SmartDecoder XP Sound as well as the available For setting options, please refer to the detailed operating instructions.

Factory reset

To restore the sound decoder to its factory settings, program CV8 to a value of 8.

Programming

Configuration variables (CVs) form the basis of all the decoder's settings. This decoder can be used with the PIKO SmartControl^{wlan}, PIKO SmartControl^{light}, DCC system, the PIKO SmartControl DCC system, or any other Motorola-based system.

For more information on programming options, please refer to the instruction manual.

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NOTE: This product is not a toy and is not suitable for children under the age of 14. Any liability for damage of any kind caused by improper use or failure to observe these instructions is excluded.

Service:

Internet: www.piko.de

E-Mail: info@piko.de

Hotline: Di + Do 16-18 Uhr

Service: If you wish to return an item, please send it to us along with a copy of the receipt and the completed return form, which you can find in our online store under "Returns and Refunds."

Warranty Statement

Each decoder module is fully tested before shipment. Nevertheless, should a malfunction occur within the 2-year warranty period, we will repair the module free of charge on presentation of the proof of purchase. This warranty is voided if the unit has been damaged by improper use. Please note that, according to the German Electromagnetic Compatibility Law (EMV-Gesetz), the decoder module may only be used inside models bearing the CE mark.

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