

CV	Description	Area	Value*
1	Locomotive address	DCC: 1 - 127 Mot: 1 - 80	3
2	Minimum speed (the speed from 0 until the locomotive is running at speed step 1)	0 - 255	0
3	Acceleration delay	0 - 255	30
4	Braking delay	0 - 255	30
5	Maximum speed (must be greater than CV 2)	0 - 255	200
6	Average speed (must be greater than CV 2 and less than CV 5)	0 - 255	100
7	Firmware version (The processor can be updated)	-	differently
8	Manufacturer's ID Decoderreset CV8 = 8	different	162
12	<b>Decoder operating mode</b>	<b>Value</b>	
	Bit 0=1 DC (analog operation; direct current) on	*1	0 - 117
	Bit 2=1 DCC data format on	*4	
	Bit 4=1 AC (analog 3-rail operation; alternating current) on	*16	
	Bit 5=1 Motorola® data format on	*32	
17	<b>Long locomotive address</b>	1 - 10239	1000
18	17 = high Byte	192 - 231	195
	18 = low Byte	0 - 255	232
27	<b>Brake signal settings (automatic stop)</b>	<b>Value</b>	
	Bit 0 = 1 -> ABC (Automatic Brake Control) right rail positive	1	0 - 51
	Bit 1 = 1 -> ABC left rail positive	2	
	Bit 4 = 1 -> DC; opposite direction of travel	16	
	Bit 5 = 1 -> DC; same direction of travel	32	
29	<b>DCC standard configuration</b>	<b>Value</b>	
	Bit 0=0 Normal direction of travel	*0	0 - 63
	Bit 0=1 Opposite direction of travel	1	
	Bit 1=0 14 speed steps	0	
	Bit 1=1 28 speed steps	*2	
	Bit 2=0 Digital mode only	0	
	Bit 2=1 Automatic analog/digital recognition	*4	
	Bit 3=0 RailCom® turned off	0	
	Bit 3=1 RailCom® turned on	*8	
	Bit 4=0 Speed steps over CV 2, 5, and 6	*0	
	Bit 4=1 Use the characteristic curve from CV 67 - 94	16	
Bit 5=0 Short address (CV1)	*0		
Bit 5=1 Long address (CV 17/18)	32		
30	<b>Error codes for the motor, thermal overload, and function outputs:</b> 1 = motor error, 2 = thermal overload error, 4 = function output error	0 - 7	0

\* set ex works


#### Function assignments

F0	Light	F7	Cab Window	F14	Sanding
F1	Engine	F8	Air Valve Release	F15	Curve Squeal
F2	Horn	F9	Coupling	F16	Clickety-Clack
F3	Switching Gear	F10	Radio 1	F17	Train Lighting: Engine pushing
F4	Hand Brakes	F11	Radio 2	F18	Train Lighting: Engine pulling
F5	Radiator Hatch	F12	Radio 3	F19	Volume Regulator
F6	Cab Door	F13	Radio 4	F20	Tunnel mode

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 #46541 PIKO SmartDecoder XP 5.1 Sound  
Next18 for Diesel locomotives TGK2 Kaluga TT  
multiprotocol

**PIKO**  
MODELLBAHNEN & GEBÄUDEMODELLE

**NOTE: Detailed information on the PIKO SmartDecoder XP 5.1 Sound is available as a PDF file on our Webshop on the page of the respective item number. The file contains a full description of all functions and operating possibilities for the new SmartDecoder XP 5.1 Sound.**

#### Description

The state-of-the-art PIKO SmartDecoder XP 5.1 Sound Next18 inside in this PIKO locomotive is a compact yet powerful multi-protocol PluX22 sound decoder. It features high fidelity, 12 bit 8-channel sound with 2.5 watts of output that ensures distortion-free sound at all levels. It complies with the current RCN standards in all areas and can be used in DCC- and Motorola® digital systems as well as traditional DC or AC analog layouts. It automatically senses what operating mode is used on your layout and is RailCom®/RailCom Plus® compatible. The PIKO SmartDecoder XP 5.1 Sound features several programmable braking distance functions in addition to numerous other programmable functions.

The PIKO SmartDecoder XP5.1 Sound is load-regulated and features auto-adaptive motor control that works with of a fundamentally newly developed traditional DC motors for a silky smooth ride as well as 1 Amp. The motor speed table can be set using the minimum, median, and maximum motor speed (simple curve), or by the user-programmable 28-speed step extended curve. The decoder features two directional lighting outputs and four (of which two logic) additional special function outputs that can be activated using function keys up to F68 (DCC). The switching (shunting) gear, with extended slow speed range, the three possible starting and braking delays, as well as the many vehicle sounds are also switchable via function keys. The sound part can control specified function outputs as well as the motor output of the decoder. For example, the lighting of a diesel locomotive flickers when the engine is started. The PIKO SmartDecoder XP 5.1 is supported by the further developed power management in case of short-term voltage loss.

#### Installing the PIKO SmartDecoder XP 5.1 Sound

Remove the jumper plug from your model's PluX18 interface. Insert the new sound decoder into the interface socket. Please install the loudspeaker as shown in the graphic of the "Spare parts list". Check for crossed wires and short circuits before and after reinstalling the shell. Place the model on your programming track with programming mode activated on your DCC system. During programming or when reading the model's DCC address, a small amount of current will flow through the model, which does not affect the decoder; even in the event of a short circuit.

#### Special function outputs A1 to A4

The decoder's special function outputs A1 to A4 can only be activated if the desired functions are already connected to the model's Next18 interface or if solder pads are available for the special function outputs on the main circuit board. Outputs A3 & A4 provide logic levels and must be wired accordingly on the main board be connected.

**A short circuit in the motor, lighting, pick-up wiper, or wheelsets can destroy the decoder as well as the electronics of the model!**

#### First-time use of the decoder (state of delivery)

Enter address 3 on your digital control system. Depending on the data format used to address the sound decoder, the locomotive runs in DCC mode with 28 speed steps or in Motorola® mode. When using a RailCom Plus® capable digital control center the decoder is detected automatically and can be operated immediately. If the decoder is used on a conventional analog layout, it can be controlled with a DC or AC power pack. The decoder will automatically detect the layout's operating mode.

**NOTE:** In DC mode, your vehicle will not start until the voltage is higher (speed control turned up further) than you may have been used to when operating with analog vehicles.

#### Function outputs in analog mode

It is possible to program the decoder so that function keys F0 - F12 (as they are assigned in the function mapping) can also be activated in analog mode. To do this, CVs 13 & 14 must first be programmed with a DCC central control unit. The corresponding values can be found in the CV table of the detailed operating instructions. The light function F0 and the engine noise F1 are switched on at the factory.

## Motorola®

The decoder utilizes 4 Motorola® addresses to access functions F1 - F 16, when using a Motorola—based command station. The three sequence addresses for the functions F5 - F16 are ascending to the decoder address and can be activated in CV61 as required by the values 1 (F5 - F8), 2 (F5 - F12), or 3 (F5 - F16).

## Configuration of CVs

CVs 12 and 29 control the operating mode and configuration CVs, respectively. As a rule, an indexed CV contains various basic settings of a decoder, such as reversing the direction of travel. CV calculation examples can be found in the detailed operating instructions.

## RailCom®, RailCom Plus®

In the sound decoder, CV29 (RailCom®) can be turned on or off via bit 3. The decoder is automatically recognized by RailCom Plus® - equipped command stations (like PIKO SmartControl) if the RailCom Plus® option is activated in CV 28. The decoder name, locomotive symbol, and special function symbols will appear automatically on your control device's screen. With RailCom Plus® technology, no locomotive data has to be stored in the DCC central control unit and no locomotive addresses have to be programmed into the decoder.

## Braking

The sound decoder understands the following braking methods:

Märklin® braking section (brakes with analog DC voltage)

DCC braking function

ABC (Automatic Brake Control) braking section

The decoder's adjustable braking distance can bring the train to a stop within a centimeter of a signal. More information on "braking behavior" can be found in the detailed operating instructions for PIKO SmartDecoder XP 5.1 Sound.

## Function outputs

A comprehensive description of all options related to the function outputs can be found in the detailed operating instructions.

## Simple and extended function mapping

Easy-to-use **function mapping** allows you to assign functions like lighting and other outputs to any key between F0 – F12. Acceleration, braking delay, and switching (shunting) mode can be assigned to any function keys using CVs 156 and 157.

## Smoke generator control

A smoke generator can be connected to the outputs A1 to A2, which is load-dependent (factory setting) and reacts to the speed dependency of the model. Function key assignment is done using extended function mapping.

## Extended function mapping

Due to its complex nature, extended **function mapping** cannot easily be set by programming individual CVs. To work with extended **function mapping**, you will need the PIKO SmartProgrammer device (#56415) and, if desired, the PIKO SmartTester (#56416). Detailed information on extended function mapping is available in the instruction manual.

## Servo control

The sound decoder enables the control of servo motors via the function outputs A1 and A2. The assignment to the function keys is done exclusively via the extended function mapping.

The use of a servo with the decoder requires electronics expertise.

Further information can be found in the detailed operating instructions.

**ATTENTION:** Soldering on the decoder should only be carried out by experienced specialists with the appropriate tools. Decoders damaged by improper handling will not be covered by the warranty.

## Sound settings

To change the overall sound volume of the SmartDecoder XP 5.1 Sound, first program CV31 to a value of 16 and CV32 to a value of 0.

This will take you to the programming area for setting the total volume. You can now set this as you wish in CV257 in the value range 0 - 255.

NOTE: In order to play a PIKO sound on the sound decoder, the test and programming device requires PIKO SmartProgrammer (#56415) and (optional) the PIKO SmartTester (#56416).

All further information about the sound section of the PIKO SmartDecoder XP 5.1 Sound as well as the available For setting options, please refer to the detailed operating instructions.

## Factory reset

To restore the sound decoder to its factory settings, program CV8 to a value of 8.

## Programming

Configuration variables (CVs) form the basis of all the decoder's settings. This decoder can be used with the PIKO SmartControllight DCC system, the PIKO SmartControl DCC system, or any other Motorola-based system.

For more information on programming options, please refer to the instruction manual.

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Motorola® is a registered trademark of Motorola Inc. Tempe, (Phoenix) Arizona / USA  
RailCom® and RailComPlus® are registered trademarks of Lenz Elektronik GmbH, 35398 Gießen

**NOTE:** This product is not a toy and is not suitable for children under the age of 14. Any liability for damage of any kind caused by improper use or failure to observe these instructions is excluded.

## Service:

Internet: [www.piko.de](http://www.piko.de)

E-Mail: [info@piko.de](mailto:info@piko.de)

Hotline: Di + Do 16-18 Uhr

In the event of a defective decoder, please return the decoder module to PIKO along with proof of purchase, the decoder address, and a short description of the problem.

## Warranty Statement

Each decoder module is fully tested before shipment. Nevertheless, should a malfunction occur within the 2-year warranty period, we will repair the module free of charge on presentation of the proof of purchase. This warranty is voided if the unit has been damaged by improper use. Please note that, according to the German Electromagnetic Compatibility Law (EMV-Gesetz), the decoder module may only be used inside models bearing the CE mark.

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