

## Smoke Generator Control

A smoke generator can be connected to outputs A1 to A2, which is controlled by the decoder depending on the load. When stationary, the output of the smoke generator has PWM according to CV133. When the locomotive is running, the output will get PWM=100%. The locomotive engine can be stopped for 0-15 seconds (start-up delay) so that the smoke generator heats up when stationary. After this time has elapsed, the locomotive starts.

## Adjustable PWM - Frequency of light and function outputs

The output voltage of a function output is pulse width modulation (PWM) at a given frequency.

The function outputs of the decoder are factory set to a frequency of 156 Hz. This frequency can be increased to 24 kHz for outputs A0 to A2. The frequency switching can be set in the CV50 in bit 3. Bit 3 = 0 -> 156Hz, Bit 3 = 1 -> 24KHz

## Control of an electric Coupling

Electrical couplings consist of the finest copper wire windings. As a rule, these react sensitively to continuous current flow because they become relatively hot. With appropriate settings, the decoder can automatically switch off the function outputs after an adjustable time without having to switch off the function key. Furthermore, the decoder can ensure that the clutch is controlled only for a short engagement torque with an adjustable high PWM in order to raise the clutch safely. After this moment, less energy is needed to keep the clutch on top. This lower PWM and the required holding time are also adjustable. If the couplings used are not safely uncoupled during the first attempt, a number of coupling repetitions can also be set. When adjusting the clutch repetitions, "as many as necessary, as few as possible" applies. To ensure that a permanent repetition does not lead to the destruction of the clutch windings, a switch-off time must be entered in steps of 0.1s, which the decoder always waits for before carrying out a further decoupling process.

CV124 = Number of coupling repetitions

CV125 = Switch-on time in 100ms steps with PWM from CV117 (A1) to CV118 (A2)

CV126 = Stopping time in 100ms steps

CV127 = Switch-off time in 100ms steps, (0=no coupling control)

CV128 = Stop PWM

CV129 = Coupling for A1 to A2

CV 129:	Value
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Bit 1	A1 for coupling	2
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Bit 2	A2 for coupling	4
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## Shunting tango, automatic decoupling drive

A maneuvering tango can only be activated if the electric clutch control via CV124-129 is activated.

A maneuvering tango is triggered by one of the clutch outputs when the decoder speed = 0:

Function of a shunting tango:

- The locomotive drives with an adjustable gearing for a certain setting in time (T1) opposite the present direction of travel. (press on)
- The locomotive stops and changes the direction of travel.
- Uncoupling procedure and locomotive drives with the same speed step for an adjustable time T2 (press on)
- The locomotive stops, now the locomotive has the original direction of travel again.

The settings for CV's are:

CV135 for the shunting tangos (1-255). The value 0 specifies that no shunting tango takes place.

CV136 for pressing time T1 in 100ms steps

CV137 for pressing time T2 in 100ms steps

## Shunting tango with automatic coupling and decoupling

Changing the mode of operation for two connected couplings on two outputs:

- In CV129, always use the least significant output A1 to A2 for the front clutch, so when using A1 and A2, use A1 for the front coupling and A2 for the rear coupling.
- If the front coupling is released by means of a function key and the driving direction is forward at this point in time, the coupling is switched off when the driving direction is reversed in the automatic maneuvering sequence (coupling procedure). If the rear clutch is released and the direction of travel is backwards at this point in time, the coupling process is also triggered now. In the opposite direction of travel, the coupling is controlled according to the setting of the automatic decoupling movement.
- The entire duration of the coupling control must be adapted to the times of the maneuvering tango in CVs 136 and 137 via CVs 124-127. CV124 \* (CV125 + CV126 + CV127) applies, it is bigger than CV136 + CV137

Here, encores may have to be made on the right side of the inequality, because in the maneuvering tango the decoder only reverses the direction of travel when it realizes that the motor is really stopped.

## Servo Control

Deployment of a servo on the decoder requires expert knowledge in electronics.

In CV166, it is specified via which output a servo is to be controlled. If the corresponding bit is set, a control signal for a model building servo is output at the desired output (SUSI). The following assignment applies to the connection pins of the SUSI interface: Servo1 = CLK, Servo2 = Data. The wiring of the outputs can be found in the FAQ PIKO in the graphic "Servo connection for operating a servo on SUSI or solder pads for PIKO SmartDecoder 4.1".

CV166	Value	
Bit 0	SUSI with servo signal	1

In CV167 (SUSI Servo1) and/or 168 (SUSI Servo2) the respective function key number F0 - F28 is entered, via which the servos are to be switched.

The servo settings and cycle time can be set with the following CVs:

CV160 Servo 1, position 1 (function key off) CV163 Servo 2, position 1 (function key off)

CV161 Servo 1, position 2 (function key on) CV164 Servo 2, position 2 (function key on)

CV162 Servo 1, rotation time in 100ms steps CV165 Servo 2, rotation time in 100ms steps

## Return to Factory Setting (Reset)

Two CVs (CV8, CV59) can be used in DCC programming and one CV (CV59) in Motorola programming to return the decoder to factory settings. If you do not want to rewrite all available areas, you can decide which areas should be set to default.

The to be programmed value 1-5 places the following CVs into factory setting:

1 = CV0 - 256, as well as CV257 - 512 (RailCom® Bank 7) CV31=0, CV32=255

2 = CV257 - 512 (RailCom Plus® Banks 5 & 6) CV31=1, CV32=0 and CV31=1, CV32=1

3 = CV257 - 512 (extended function Mapping Banks 1 & 2) CV31=8, CV32=0 and CV31=8, CV32=1

4 = CV257 - 512 (PWM-Modulation Function outputs banks 3 & 4) CV31=8, CV32=3 and CV31=8, CV32=4

## Programming

Configurations variables (CVs) form the basis of all possible settings of the decoder. The decoder can be programmed with DCC and Motorola control panels.

## Technical Data

Addresses: 1-9999 (extended DCC address)

Max. motor current / Load: 0.8 A\* short-term to 2 A

Function outputs: 0.4 A each

Size: 14,7 x 8,6 x 2,9 mm

\*Continuous load, may vary depending on the installation situation

**Note:** This product is not a toy and is not suitable for children under the age of 14. Any liability for damages of any kind caused by improper use or not observing these instructions is excluded.

CV	Description	Range	Value
1	<b>Loco address</b>	DCC: 1 - 127 Motorola: 1 - 80	03
2	<b>Minimum speed</b> (change, until the loco drives with speed step 1)	1 - 63	01
3	<b>Acceleration</b> 1 means that every 5ms the actual speed is increased by 1. If the internal maximum speed is set to 200 (CV5=50 or CV94=200), then the acceleration from 0 to Fmx is 1sec.	0-255	15
4	<b>braking interia</b> (time factor like CV3)	0-255	15
5	<b>Maximum speed</b> (must be greater than CV2)	1 - 63	63
6	<b>Middle speed</b> (must be greater than CV 2 and less than CV5)	1 - 63	24
7	<b>Software version</b> (the processor can be updated)	-	different
8	<b>Manufacturer ID</b> Decoder reset, values as CV59	different	162
17	<b>Expensive loco address</b> 17 = High Byte 18 = Low Byte	1 - 9999	2000
18		192 - 231	199
		0 - 255	208
30	Error memory for function outputs, motor and temperature monitoring 1 = fault function outputs, 2 = fault motor, 4 = overtemperature	0-7	0
31	1. Marker CV for CV-Banks	0, 1, 8	0
32	2. Marker CV for CV-Banks	0,1,3,4,5,255	255
33-46	<b>Simple Function Mapping</b> <b>Relation of the function outputs to the CVs</b> CV 33 Light function key (F0) forwards CV 34 Light function key (F0) backwards CV 35 Function key F1 CV 36 Function key F2 CV 37 Function key F3 CV 38 Function key F4		1 2 4 8 16 32
59	<b>Reset to factory defaults</b> (even with CV8) 1 = CV 0 - 256, as well as CV257 - 512 (RailCom® bank 7) 2 = CV 257 - 512 (RailCom Plus® banks 5 & 6) 3 = CV 257 - 512 (extended function mapping banks 1 & 2) 4 = CV 257 - 512 (PWM-Modulation function output banks 3 & 4)	0 - 4	0

## Note:

You can find a detailed instruction manual for the PIKO SmartDecoder 4.1 on the web page of the respective product in our web shop.

## Service:

Internet: [www.piko.de](http://www.piko.de)

E-Mail: [info@piko.de](mailto:info@piko.de)

Hotline: Di + Do 16-18 Uhr

In case of a possible defect, please send us the module with the proof of purchase, a short error description and the decoder address.

## Warranty Declaration

Each component is checked for its complete functionality before delivery. Should an error nevertheless occur within the warranty period of 2 years, we will repair the module free of charge upon presentation of the proof of purchase. The warranty claim is void if the damage was caused by improper handling. Please note that, according to the EMC law, the module may only be operated within vehicles bearing the CE mark.

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PIKO SmartDecoder 4.1 Sound Next18



## Description

This locomotive decoder is a small, high performance multiprotocol decoder. It can be used with DCC-, Selectrix- and Motorola digital systems and also operates in analog mode with AC or DC currents. The individual mode of operation is automatically recognized, but can also be set manually.

The decoder works on a frequency of 18,75 kHz and is therefore not only suitable for DC current but also for bell-shaped armature motors (e. g. Faulhaber, Maxon, Escap) up to a continuous current consumption of 0.8 A. Short-term higher motor currents up to 2 A are well tolerated.

The decoder is also RailCom® and RailCom Plus® capable and is in command of ABC braking as well as ABC Slow Running. Setting of the motor characteristics is done via minimum, medium and maximum speed (simple characteristic) or via the extended characteristic with individual adjustments for 28 drive positions.

The decoder has two headlight outputs depending upon direction of travel and (depending on decoder version) up to four additional special function outputs. Over and above that, there are 3 sensor inputs, e.g. Reed Contacts or Hall Type Sensors on the decoder, two are in the SUSI-Interface with one as a solder pad. Slow moving extended shunting operations and the three possibilities in starting out and brake action delays can be set by function keys.

## Characteristics

- Multiprotocol decoder with load control for DCC, Motorola and Selectrix
- Suitable for DC current and bell-anchor motors up to 0.8 A.
- Quiet motor running by motor control with 18.75 kHz
- 14, 27, 28, 128 gears, depending upon data format.
- Short (1-127) and long (128-9999) addresses
- NMRA conformity
- RailCom® and RailCom Plus®
- Adjustable minimum, maximum and medium speeds.
- Extended driving gear characteristics are adjustable.
- Shunting gear (half-speed) adjustable.
- 3 settings for startup and brake delay, individually adjustable via F0 - F28
- Headlight outputs in direction of travel dimmable.
- 2 Special function outputs, dimmable and adjustable in direction of travel.
- 4 logical outputs
- Adjustable activation of the light- and function outputs adjustable for analog operation.
- Second dim function for lights adjustable from A1 and A2.
- Simple function mapping F0 - F12 for lighting A1 and A2, startup, brake delay and shunting operations.
- Extended Function Mapping, F0 - F44 for switching multiple outputs depending on linked conditions
- Train illumination disengageable.
- Function outputs: Blinking with variable shutoff time.
- Function exists: 2 phase for alternative flashers.
- Load dependent smoke generator controls.
- Firebox with adjustment parameters for brightness changes and flicker rhythm.
- Shunting coupling and shunting tango.
- Fading in, or out of the lighting- and function outputs, adjustable.
- Energy saving lighting effect: After attaining maximum brightness after time setting.
- Fluorescent lighting, switching-on effect with adjustable flash time and –number.
- 8 PWM banks with 64 modulation entries each for e. g. American light effects such as Mars Light, Gyra Light, Strobe etc.
- With Micro-SUSI Socket for respective PIKO Sound-Module, function decoder and servo signal.
- Brakes with DCC braking signal, braking track with DC current or ABC-Brakes.
- ABC-Slow Moving Distance with LENZ BM2
- 2 settings for braking distance in cm, activated by ABC-, DC- and DCC-brake signal, as well with driving speed 0 with adjustable speed level step.
- 2 motor control types for a precise motor control with many control settings
- Motorola with 3 points for the functions F1 - F12 by deploying the Motorola-Centers (e.g. 6021)
- All outputs are secured against short circuits.
- Error memory for motor and function outputs as well as temperature shutoff.
- Conventional DC operation with automatic switch-over to the individual mode of operation.
- All CVs must be programmed with digital devices with DCC formats and Motorola.
- In DCC-operation, programmable per register, CV directly or page programming.
- Main track programming (DCC)
- Decode programming lock.

## Connection of the PIKO SmartDecoder 4.1

Remove the socket plug from the Next18 interface of your vehicle. Stick the locomotive decoder carefully into the same place of the interface socket.

Make sure that no conductive connection is possible anywhere. Make sure that no short-circuits can occur even after closing the locomotive. The first start-up should be carried out on the programming track when the programming mode of the control unit is called up. Usually very small currents flow during reading or programming, which do not damage the decoder in the event of a short circuit.

## Special Functions A1 and A2

The special functions A1 and A2 of the decoder can only be used when the designated user are already connected to the interfaces Next18 in the vehicle or on when there are solder pads available on the main circuit board.

**A short circuit with the motor, lighting, third rail pickup and wheels can destroy the device and eventually the locomotive electronics!**

## SUSI Interface

The SUSI Interface of this decoder is executed via the Next18 Interface. If the main circuit board of the vehicle is equipped with a SUSI-Interface, then either an PIKO Sound-Module with SUSI, or a suitable function decoder or two servo switchings can be connected to it.

Which CV must be programmed for the individual use can be seen in the CV-Chart.

In the factory setup, the decoder at the SUSI-Interface provides data for an PIKO Sound-Module.

**CAUTION:** Soldering on the decoder should only be performed by experienced experts with proper tools. For decoders which were damaged by improper handling, any warranty becomes void.

## Decoder Startup (delivered condition)

Enter address 3 into the control unit. The decoder operates depending on the data format used in DCC-Operation with 28 speeds or in Motorola operation. With a RailCom Plus<sup>®</sup> capable digital center, the decoder is up and running within a few seconds and can be operated immediately. If the decoder is used on conventional systems, it can be controlled with a DC or AC drive unit. The operating mode is automatically recognized by the decoder. The status of functions F0 - F12 can be set for analog operation via CVs 13 and 14.

## Analog Operation with AC or DC Voltage

The locomotive decoder is suitable for analogue operation with DC or AC voltage, which is self-detected.

**NOTE:** In DC operation, your vehicle will only start up at higher voltage (speed controller turned up further) than you might have been used to in operation with analogue vehicles.

## Function outputs in analog operation

It is possible to set the decoder in such a way that the function keys F0 - F12, as assigned in Function Mapping, can also be switched on in analog mode. For this purpose, CVs 13 & 14 must first be programmed with a digital control unit. The corresponding values can be found in the CV table.

## Motorola

In order to be able to reach the functions F1 - F12 when used with Motorola command stations, the decoder has 3 Motorola addresses, which are stored trinary in CV47-49. These 3 addresses are also used for decoding. If an address is programmed decimal in CV1, the decoder automatically stores the trinary equivalent in CV47 up to address 79. For example, in order to use Motorola locomotive addresses up to 255, CVs 47 - 49 must be programmed directly decimal via Motorola programming.

These CVs can be read but not programmed on the DCC programming track.

If the CV47 is programmed via Motorola, CV1 is not changed and therefore the DCC data format in CV12 is switched off, so that the decoder cannot be accessed by mistake via 2 addresses.

If bit 5 (DCC long address) is set in CV29, the Motorola data format is switched off except for Motorola programming, so that the decoder cannot react to 2 addresses.

## Configurations-CVs

Besides the decoder address, the configuration CVs of a locomotive decoder are certainly the most important CVs. These are the CVs 29,50 and 51 of the PIKO SmartDecoder 4.1, and a configuration CV usually contains different settings of a decoder, which are displayed in a maximum of 8 bits (0 - 7). The value to be entered for a CV is calculated from the respective CV table by adding the values of the desired functions. The following table shows you the meaning and content of the configuration CVs, as well as an example calculation of the value:

Bit	Configuration CV29	default
0	normal direction reversed travel	0 1
1	14 / 27 speed steps 28 / 128 speed steps	0 2
2	only digital operation automatic analogue / digital switching	0 4
3	RailCom <sup>®</sup> switched off RailCom <sup>®</sup> switched on	0 8
4	speed steps from CV2, 5 and 6 speed characteristics from CV67 to 94	0 16
5	short address (CV1) long address (CV 17/18)	0 32

Bit	Configuration CV50	Value
0	Motorola 2. address not use Motorola 2. address use	0 1
1	Motorola 3. address not use Motorola 3. address use	0 2
2	light output not switch light output switch	0 4
3	Frequenzy Light, A1 to A2 = 156Hz Frequenzy Light, A1 to A2 = 24KHz	0 8
4	FSUSI = SUSI SUSI = A3/A4 Logic level	0 16
5	KSUSI = SUSI SUSI DATA = Input 1, CLK = Input 2	0 32

## Example (CV 29):

Normal driving direction	Value = 0
28 Speed steps	Value = 2
Auto. Analog/Digital detection	Value = 4
RailCom <sup>®</sup> off/on	Value = 8
Speed steps using CV 2, 5, 6	Value = 0
Short address	Value = 0

he sum of all the values is 14.

This value is set to CV29 as factory default value.

CV139 = Braking distance in cm

CV140 = alternative braking distance, can be activated via the CROSS bit (see "Advanced Function Mapping")

CV141 = maximum speed of the model locomotive in cm/s

CV142 = If the value determined for CV141 exceeds 255, the remainder is entered in CV142 (possibly track 1 1lm (G).

CV143 = Activation of the constant braking distance by:

Bit 0 = 1 -> reference speed = 0, with current internal speed according to CV138 and higher

Bit 1 = 1 -> ABC Brakes

Bit 2 = 1 -> DC Brakes

Bit 3 = 1 -> DCC Brake signal

CV143 = 0 -> No constant brake distance

If braking is initiated with a constant braking distance, the decoder does not react to driving commands again until the locomotive has come to a standstill. This process can be interrupted by switching on the shunting gear.

## Determining the maximum speed of the model locomotive.

Program the CV of the maximum speed in the decoder to the maximum possible value (CV5 = 63, or when using the extended gear stage characteristic CV94 = 255)

Mark a starting point on a sufficiently long, straight track section from which the vehicle can drive for approx. 2 seconds without hindrance at the possible maximum speed. Lay down a folding rule (inch rule) at the selected starting point. Now enter this section at maximum speed, e.g. the speed governor is set to the highest speed. When you reach the starting point, start the time measurement for 2 seconds. After these 2 seconds have elapsed, note the position of the vehicle on the yardstick and read the value in cm. Divide this value by 2 and you will get the speed in cm/s. This value is now entered in CV141. In the track widths 1 and 1lm (G) for very fast vehicles, the determined value may possibly exceed 255. In this case, please enter the value 255 in CV141 and the rest of the determined value in CV142.

After this measurement, the CV for maximum speed (CV5 or CV94) can be set to the desired maximum speed for driving.

## Function Outputs

### Simple Function Mapping

The following settings of the decoder are only possible with simple function mapping (CV 96 = 0).

In the simple function mapping, the assignments of switching tasks such as lighting, special function outputs, shunting gear and switchable starting and braking delay can be freely assigned to the function keys F0 to F12 of the digital control center. The value that is written to a CV of the function mapping determines the functions that can be switched using a function key assigned to the CV. The CVs 33 to 46 serve this purpose according to the following scheme.

Assignment of Function keys to the CVs	Default	Assignment of the Bits	Value
CV 33	Light function key F0 forwards	Bit 0	Light function key front 1
CV 34	Light function key F0 backwards	Bit 1	Light function key back 2
CV 35	Function key F1	Bit 2	Function key A1 4
CV 36	Function key F2	Bit 3	Function key A2 8
CV 37	Function key F3	Bit 6	Shunting 64
CV 38	Function key F4	Bit 7	Starting-/brake delay 128
CV 39	Function key F5		
CV 40	Function key F6		
CV 41	Function key F7		
CV 42	Function key F8		
CV 43	Function key F9		
CV 44	Function key F10		
CV 45	Function key F11		
CV 46	Function key F12		

Example 1: The rear light output should only be switched with the function key F5.

The CV to be programmed is CV39 for function key F5, in which the value 2 (rear light output) is programmed. So that the rear light output is no longer switched backwards in the direction of travel via function key F0, CV34 must also be programmed for function key F0 in the direction of travel backwards to the value 0.

Example 2: The function output A1 and the shunting gear are to be switched together with the function key F10.

The CV to be programmed is CV44 for function key F10, in which the value 4 (function output A1) plus 64 (shunting gear) is programmed, e.g. the value 68. So that the function output A1 is no longer switched via function key F1 and the shunting gear no longer via function key F5, CVs 35 for function key F1 and 39 for function key F5 must also be programmed to the value 0.

## Simple and extended Function Mapping

The following settings of the decoder are possible for simple (CV96 = 0) and extended (CV96 = 1) function mapping.

## Dimming of Light and Function Outputs

The light and function outputs A1 to A2 can be set to any dimming level. These settings are stored in CVs 116 (Light) and 117 (A1) to 118 (A2).

## Softly fade in and out light and function outputs

If the output is switched on or off, it is softly faded in or out.

In CV186, you can specify which output should receive this dazzle function.

	Value	
Bit 0	Light output with dazzle function	1
Bit 1	A1 with dazzle function	2
Bit 2	A2 with dazzle function	4

A combination (total of the single values) is individually possible.

The setting of the CV187 determines how fast the glare function should work. The step size is CV value \* 1ms.

## Blinking of the Light- and Function Outputs

The locomotive decoder has a flashing generator which can be assigned to the outputs. Both the switch-on and switch-off time of the flashing generator can be set separately from each other.

In CV109, you can specify which output is to use the flash generator. In addition, the CV110 can be used to determine which output is to use the blinking generator with 180° phase rotation. For example, a variable flasher can be implemented.

CV 109:	Value	CV 110:	Value
Bit 0	Light output w/ flashing generator	Bit 0	Light output w/ flashing generator 180°
Bit 1	A1 with flashing generator	Bit 1	A1 with flashing generator 180°
Bit 2	A2 with flashing generator	Bit 2	A2 with flashing generator 180°

A combination (total of the single values) is individually possible.

In CV111 the switch-on time can be set in steps of 100ms and in CV112 the switch-off time in steps of 100ms.

## Turn-on Effect of a Neon Tube / Fluorescent Tube

The switch-on effect of a defective fluorescent lamp can also be output at the light and function outputs. This effect consists of an adjustable, maximum number of flashes (accidentally a flash up to a maximum number of flashes) and an adjustable flash time, e.g. how fast the flashes should follow each other.

CV 188:	Value
Bit 0	Light output w/ fluorescent lamp effect 1
Bit 1	A1 w/ fluorescent lamp effect 2
Bit 2	A2 w/ fluorescent lamp effect 4

A combination (sum of the single values) is of course also possible here.

The flash time is set in 5ms increments via CV 189. The maximum number of flashes in CV 190.

## Energy-saving lamp effect when switching on the light and function outputs

When an energy-saving lamp is switched on, it first produces a basic brightness before it slowly reaches its maximum brightness. This effect can be assigned to the outputs of the decoder as follows.

CV 183:	Value
Bit 0	Light output as energy-saving lamp 1
Bit 1	A1 as energy-saving lamp 2
Bit 2	A2 as energy-saving lamp 4

**A combination (total of the single values) is of course again possible here. The basic brightness can be adjusted via CV184. The setting of CV185 determines how fast the final brightness value (PWM1 in CVs 116 - 120) should be reached. The step size is CV value \* 5ms. The basic brightness can be adjusted via CV184.**

## Firebox flickering

The outputs light, A1 to A2 can be assigned a random flickering. This effect is used for example for the flickering of a firebox.

CV 181:	Value	
Bit 0	Light output with flickering	1
Bit 1	A1 with flickering	2
Bit 2	A2 with flickering	4

A combination of (the total of the single values) is of course possible here again.

In CV182, the settings for the flicker rhythm and the brightness change are entered:

Bits 0 - 2 change the flicker rhythm (value range 1 to 15).

With the value 128 the output is always bright, but can be combined with the value range 16 to 112.

As only one value can be programmed in a CV, the flickering results from the sum of the single values of the flicker rhythm plus the sum of the single values of the brightness (sum of bits 0 -3 plus sum of bits 4 - 6).

The combination of all bits leads to different random flicker images. The rule here is "try it out".